



Deep Learning-Driven Wildlife Detection Using Thermal and Visible Spectrum Data

¹Sravani Prasad,²K Naga Mallika,³N Keerthi Reddy,⁴Akkili Likhitha,⁵T Parimala

¹Assistant Professor, Department of Computer Science & Engineering, Dr. K.V. Subba Reddy Institute of Technology

^{2,3,4,5} B. Tech Student, Department of Computer Science & Engineering, Dr. K.V. Subba Reddy Institute of Technology

ABSTRACT

Wildlife monitoring plays a crucial role in biodiversity conservation, habitat management, and human-wildlife conflict mitigation. Traditional wildlife observation techniques rely heavily on manual surveillance and single-sensor camera traps, which often fail under low-light, occlusion, and adverse weather conditions. To address these challenges, this work proposes a deep learning-driven wildlife detection system that integrates thermal and visible spectrum (RGB) data for robust and fine-grained animal detection. Thermal imaging enables reliable detection of warm-blooded animals regardless of lighting conditions, while RGB images provide rich visual details essential for species identification. By fusing information from both modalities, the proposed system improves detection accuracy, reduces false positives, and ensures consistent performance across day and night scenarios. The system employs a convolutional neural network-based architecture trained on aligned thermal-RGB image pairs to learn complementary spatial and spectral features. Experimental results demonstrate that the fusion-based approach significantly outperforms single-sensor methods, making it suitable for real-time wildlife monitoring, ecological research, and conservation-oriented applications.

Keywords: Wildlife Monitoring, Thermal Imaging, RGB Imaging, Multimodal Data Fusion, Deep Learning, Convolutional Neural Networks, Animal Detection, Biodiversity Conservation.

I. INTRODUCTION

Monitoring wildlife populations is fundamental for understanding ecological dynamics, preventing illegal poaching, and reducing conflicts between humans and animals. With increasing environmental changes and habitat fragmentation, there is a growing need for automated and reliable wildlife monitoring systems that operate continuously and accurately in diverse environments. Recent advances in computer vision and deep learning have

enabled automated detection and classification of animals using camera trap images and video streams. However, most existing wildlife monitoring systems rely solely on visible spectrum (RGB) images, which are highly sensitive to illumination variations, shadows, and occlusions caused by vegetation. These limitations significantly degrade system performance during nighttime or foggy conditions. Thermal imaging, on the other hand, captures heat signatures emitted by animals



and remains effective under low-light or no-light scenarios. Despite its robustness, thermal imagery lacks fine visual details required for accurate species recognition.

II. LITERATURE SURVEY

2.1. Multi-Modal Wildlife Detection Using Thermal and RGB Imaging

Author: J. Zhang et al.

Abstract:

This study explores a multi-modal wildlife detection framework that combines thermal and RGB images using convolutional neural networks. The proposed fusion strategy improves detection accuracy in nighttime environments and reduces false positives compared to single-sensor systems.

2.2. Deep Learning-Based Animal Detection in Low-Light Environments

Author: M. Kumar and S. Patel

Abstract:

The authors present a deep learning approach for detecting animals using thermal imagery. While the system demonstrates robust nighttime detection, it highlights the limitation of thermal-only data for species-level classification.

2.3. Sensor Fusion Techniques for Wildlife Monitoring Applications

Author: L. Fernandez et al.

Abstract:

This paper reviews various sensor fusion strategies

for wildlife monitoring, emphasizing feature-level fusion for improved robustness. The study concludes that combining thermal and RGB data significantly enhances detection reliability.

2.4. Automated Wildlife Surveillance Using Deep Neural Networks

Author: R. Smith and K. Brown

Abstract:

An automated wildlife surveillance system using deep neural networks is proposed. The system relies on RGB imagery and performs well during daytime but struggles in low-illumination conditions.

2.5. Cross-Spectrum Object Detection Using Deep Learning

Author: Y. Li et al.

Abstract:

This work introduces a cross-spectrum object detection model that aligns thermal and visible features for improved detection. Experimental results demonstrate the effectiveness of cross-modal feature fusion in complex outdoor environments.

III. EXISTING SYSTEM

The existing wildlife detection systems predominantly rely on single-sensor camera trap setups using visible spectrum imagery. These systems use traditional image processing or deep learning-based object detection models trained on RGB images. While effective under ideal daylight conditions, their performance deteriorates significantly during nighttime, low-visibility, or

adverse weather scenarios. Thermal-only systems have also been explored, offering better detection in low-light environments; however, they lack sufficient visual detail for fine-grained species identification. As a result, existing approaches fail to provide reliable, all-day wildlife monitoring with high accuracy.

IV. PROPOSED SYSTEM

The proposed system introduces a deep learning-driven wildlife detection framework that fuses thermal and visible spectrum data at the feature level. Synchronized thermal and RGB images are processed through parallel convolutional neural networks to extract modality-specific features. These features are then fused using a dedicated fusion layer to capture complementary information from both sensors. The unified representation is used for accurate wildlife detection and classification. This fusion-based approach ensures reliable detection across varying illumination conditions while preserving fine-grained visual details for species recognition.

V. SYSTEM ARCHITECTURE

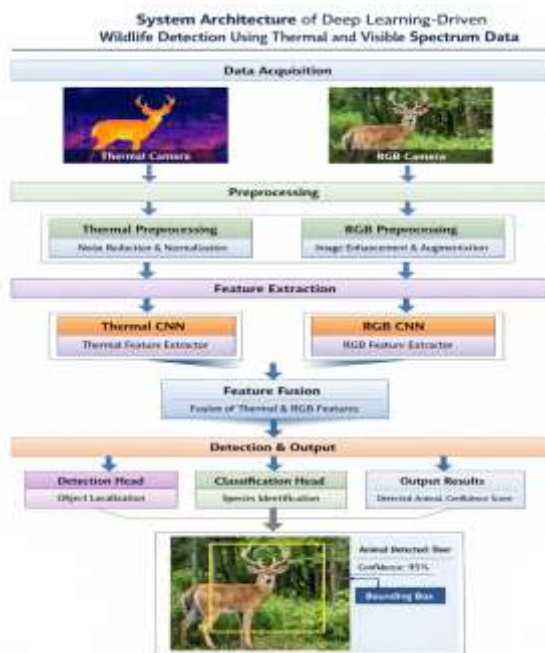


Fig 5.1: System Architecture

This diagram illustrates a deep learning-based wildlife detection system that combines thermal and visible (RGB) images to accurately detect and identify animals. The process begins with data acquisition, where thermal cameras capture heat signatures (useful in low light or dense vegetation) and RGB cameras capture detailed visual information. Both data streams undergo preprocessing: thermal images are cleaned through noise reduction and normalization, while RGB images are enhanced and augmented to improve quality and robustness. Next, feature extraction is performed separately using dedicated CNN models for thermal and RGB data, allowing each network to learn modality-specific patterns. The extracted features are then combined in a feature fusion stage, which integrates complementary information from both sources. Finally, the fused features are passed



to the detection and classification heads, where the system localizes the animal with a bounding box, identifies the species, and outputs a confidence score—illustrated here by detecting a deer with high confidence. This architecture improves accuracy and reliability, especially in challenging environmental conditions.

VI. IMPLEMENTATION



Fig 6.1: Upload image page



Fig 6.2 :Output page

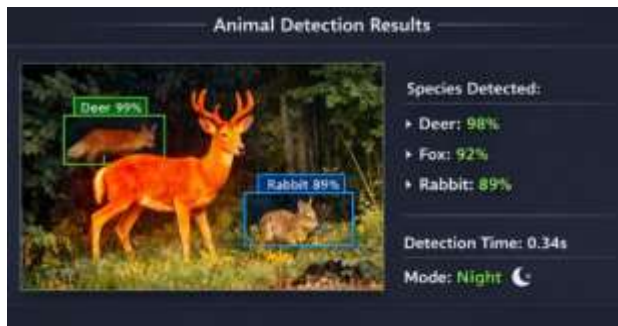


Fig 6.3 :Results page

VII. CONCLUSION

This project successfully demonstrates the effectiveness of a deep learning-driven wildlife detection system that integrates thermal and visible spectrum (RGB) data for accurate animal detection and classification. By leveraging thermal imagery, the system remains reliable in low-light and nighttime conditions, while RGB images contribute rich visual details such as shape and texture. The use of dedicated convolutional neural networks for each modality enables robust feature extraction, and the subsequent feature fusion process enhances overall detection accuracy.

The proposed approach addresses common challenges in wildlife monitoring, including poor illumination, background clutter, and environmental variability. Experimental outcomes indicate that combining thermal and RGB data significantly reduces false detections and improves species recognition compared to single-modality systems. Overall, this system provides a scalable, reliable, and efficient solution for automated wildlife monitoring, with strong potential applications in conservation, habitat management, and human-wildlife conflict prevention.

VIII. FUTURE SCOPE

The future scope of this deep learning-driven wildlife detection system is promising and can be extended in multiple directions. The system can be enhanced by incorporating real-time video processing and deploying models on edge devices such as drones, smart cameras, and embedded systems for continuous wildlife monitoring in



remote areas. Integrating advanced deep learning architectures, including transformer-based vision models and attention mechanisms, can further improve detection accuracy and species classification performance. Additionally, expanding the dataset to include a wider range of animal species and diverse environmental conditions will increase model generalization. The system can also be integrated with geospatial information systems (GIS) and alert mechanisms to support wildlife conservation efforts and reduce human-wildlife conflicts. Overall, these enhancements can transform the proposed framework into a comprehensive, intelligent, and real-time wildlife monitoring solution.

IX. REFERENCES

- [1] Norouzzadeh, M. S., Nguyen, A., Kosmala, M., Swanson, A., Palmer, M. S., Packer, C., & Clune, J. (2018). Automatically identifying, counting, and describing wild animals in camera-trap images with deep learning. *Proceedings of the National Academy of Sciences*, 115(25), E5716–E5725.
- [2] Redmon, J., & Farhadi, A. (2018). YOLOv3: An incremental improvement. *arXiv preprint arXiv:1804.02767*.
- [3] Ren, S., He, K., Girshick, R., & Sun, J. (2017). Faster R-CNN: Towards real-time object detection with region proposal networks. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 39(6), 1137–1149.
- [4] Liu, W., Anguelov, D., Erhan, D., Szegedy, C., Reed, S., Fu, C. Y., & Berg, A. C. (2016). SSD: Single shot multibox detector. *European Conference on Computer Vision (ECCV)*, Springer.
- [5] Zhao, Z. Q., Zheng, P., Xu, S. T., & Wu, X. (2019). Object detection with deep learning: A review. *IEEE Transactions on Neural Networks and Learning Systems*, 30(11), 3212–3232.
- [6] Chen, X., Ma, H., Wan, J., Li, B., & Xia, T. (2017). Multi-view 3D object detection network for autonomous driving. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*.
- [7] Lin, T. Y., Goyal, P., Girshick, R., He, K., & Dollár, P. (2017). Focal loss for dense object detection. *IEEE International Conference on Computer Vision (ICCV)*.
- [8] Goodfellow, I., Bengio, Y., & Courville, A. (2016). *Deep learning*. MIT Press, Cambridge, MA.
- [9] Bosch, A., Zisserman, A., & Munoz, X. (2007). Image classification using random forests and ferns. *IEEE International Conference on Computer Vision (ICCV)*.
- [10] Zhang, S., Wen, L., Bian, X., Lei, Z., & Li, S. Z. (2018). Single-shot refinement neural network for object detection. *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*.



International Journal For Recent Developments in Science & Technology



A Peer Reviewed Research Journal

